

Name: Solutions

Directions: Show all work. No credit for answers without work.

1. [2 points] Given
- \mathbf{y}
- and
- \mathbf{v}
- below, decompose
- \mathbf{y}
- as
- $\mathbf{y} = c\mathbf{v} + \mathbf{z}$
- where
- c
- is a scalar and
- $\mathbf{z} \cdot \mathbf{v} = 0$
- .

$$\mathbf{y} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad \mathbf{v} = \begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix}$$

$$c = \frac{\mathbf{y} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} = \frac{(1)(-1) + (2)(3) + (3)(1)}{(-1)^2 + 3^2 + 1^2} = \frac{-1 + 6 + 3}{1 + 9 + 1} = \frac{8}{11}, \quad \mathbf{z} = \mathbf{y} - c\mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \frac{8}{11} \begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix}$$

$$= \frac{1}{11} \begin{bmatrix} 11 \\ 22 \\ 33 \end{bmatrix} - \frac{8}{11} \begin{bmatrix} -8 \\ 24 \\ 8 \end{bmatrix} = \frac{1}{11} \begin{bmatrix} 19 \\ -2 \\ 25 \end{bmatrix}$$

$$\text{So } \hat{\mathbf{y}} = \frac{-8}{11} \mathbf{v} + \frac{1}{11} \begin{bmatrix} 19 \\ -2 \\ 25 \end{bmatrix}$$

2. [2 parts, 2 points each] Define
- $\mathbf{v}_1, \mathbf{v}_2, \mathbf{y}$
- as follows and let
- $W = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$
- .

$$\mathbf{v}_1 = \begin{bmatrix} 2 \\ -2 \\ 1 \\ 3 \end{bmatrix} \quad \mathbf{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix}$$

- (a) Find
- $\text{proj}_W(\mathbf{y})$
- .
- Note:
- $\mathbf{v}_1 \cdot \mathbf{v}_2 = (-2) + (-2) + 1 + 3 = 0$
- so
- $\{\mathbf{v}_1, \mathbf{v}_2\}$
- is an orthogonal basis for
- W
- .

$$\text{proj}_W \mathbf{y} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2, \quad c_j = \frac{\mathbf{y} \cdot \mathbf{v}_j}{\mathbf{v}_j \cdot \mathbf{v}_j}. \quad c_1 = \frac{-2 + 2 + 9}{4 + 4 + 1 + 9} = \frac{9}{18} = \frac{1}{2}, \quad c_2 = \frac{1 + 2 + 3}{1 + 1 + 1 + 1} = \frac{6}{4} = \frac{3}{2}$$

$$\text{So } \mathbf{y} = \frac{1}{2} \begin{bmatrix} 2 \\ -2 \\ 1 \\ 3 \end{bmatrix} + \frac{3}{2} \begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2 - 3 \\ -2 + 3 \\ 1 + 3 \\ 3 + 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 4 \\ 6 \end{bmatrix}$$

- (b) Find the distance from
- \mathbf{y}
- to
- W
- .

$$\text{dist}(\mathbf{y}, W) = \|\mathbf{z}\|, \quad \text{where } \mathbf{z} = \mathbf{y} - \hat{\mathbf{y}} = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 4 \\ 6 \end{bmatrix} = \frac{1}{2} \left(\begin{bmatrix} 0 \\ 2 \\ 4 \\ 6 \end{bmatrix} - \begin{bmatrix} -1 \\ 1 \\ 4 \\ 6 \end{bmatrix} \right) = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{So } \|\mathbf{z}\| = (\mathbf{z} \cdot \mathbf{z})^{1/2} = \left(\left(\frac{1}{2}\right)^2 + \left(\frac{1}{2}\right)^2 + 0^2 + 0^2 \right)^{1/2} = \left(\frac{1}{4} + \frac{1}{4} + 0 \right)^{1/2} = \left(\frac{1}{2} \right)^{1/2}$$

$$= \frac{1}{\sqrt{2}} = \frac{\sqrt{2}}{2}$$

3. [1 point] Let W be a subspace of \mathbb{R}^n . Suppose that $\mathbf{y} = \hat{\mathbf{y}}_1 + \mathbf{z}_1 = \hat{\mathbf{y}}_2 + \mathbf{z}_2$ where $\hat{\mathbf{y}}_1, \hat{\mathbf{y}}_2 \in W$ and $\mathbf{z}_1, \mathbf{z}_2 \in W^\perp$. Prove that $\hat{\mathbf{y}}_1 = \hat{\mathbf{y}}_2$ and $\mathbf{z}_1 = \mathbf{z}_2$. [Hint: begin with $\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2 = \mathbf{z}_2 - \mathbf{z}_1$ and take the dot product with an appropriate vector on both sides.]

Since W is a subspace and $\hat{\mathbf{y}}_1, \hat{\mathbf{y}}_2 \in W$, we have $\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2 \in W$. So

$$\begin{aligned} \hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2 = \mathbf{z}_2 - \mathbf{z}_1 &\Rightarrow (\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2) \cdot (\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2) = (\mathbf{z}_2 - \mathbf{z}_1) \cdot (\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2) \\ &= \mathbf{z}_2 \cdot (\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2) - \mathbf{z}_1 \cdot (\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2) \\ &= 0 - 0 = 0, \end{aligned}$$

since \mathbf{z}_1 and \mathbf{z}_2 are orthogonal to each vector in W . So $\|\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2\| = ((\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2) \cdot (\hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2))^{1/2} = 0$ which implies $\hat{\mathbf{y}}_1 = \hat{\mathbf{y}}_2$. So $\mathbf{z}_2 - \mathbf{z}_1 = \hat{\mathbf{y}}_1 - \hat{\mathbf{y}}_2 = \vec{0}$ and therefore $\mathbf{z}_1 = \mathbf{z}_2$ also.

4. [3 parts, 1 point each] True/False. In the following, A and B are $n \times n$ matrices. Justify your answer.

(a) If A has orthogonal columns, then A^T also has orthogonal columns.

False. For example, if $A = \begin{bmatrix} 1 & 2 \\ 1 & -2 \end{bmatrix}$ then A has orthogonal columns $(1)(2) + (1)(-2) = 0$

but $A^T = \begin{bmatrix} 1 & 1 \\ 2 & -2 \end{bmatrix}$ and so the columns of A^T are not orthogonal $(1)(1) + (2)(-2) = -3 \neq 0$.

(b) A has orthonormal columns if and only if $A^T A = I$.

True: Suppose $A = [v_1 \dots v_n]$. Then the entry of $A^T A$ in the i th row and j th column is $v_i \cdot v_j$. When $\{v_1, \dots, v_n\}$ is an orthonormal set, $v_i \cdot v_j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$ and so $A^T A = I$. Conversely, if $A^T A = I$, then $v_i \cdot v_j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$, which implies $\{v_1, \dots, v_n\}$ is an orthonormal set.

(c) If A and B have orthonormal columns, then so does AB .

True. Since A and B have orthonormal columns, we have $A^T A = I$ and $B^T B = I$.

So $(AB)^T (AB) = B^T A^T A B = B^T I B = B^T B = I$. Therefore AB also has orthonormal columns.