

1. Write the following functions as a product of two trigonometric functions.

(a)  $\cos(2t) + \cos(3t)$

$$\begin{aligned} \textcircled{1} \quad \cos(\alpha + \beta) &= \cos \alpha \cos \beta - \sin \alpha \sin \beta \\ \cos(\alpha - \beta) &= \cos \alpha \cos \beta + \sin \alpha \sin \beta \\ &= \cos \alpha \cos \beta + \sin \alpha \sin \beta \end{aligned}$$

$$\cos(\alpha + \beta) + \cos(\alpha - \beta) = 2 \cos \alpha \cos \beta$$

$$\begin{array}{l} \textcircled{2} \quad \alpha + \beta = 2t \\ \alpha - \beta = 3t \\ \hline 2\alpha = 5t \\ \alpha = \frac{5}{2}t \end{array} \quad \left| \quad \begin{array}{l} \textcircled{3} \quad \beta = 2t - \alpha \\ = \frac{4}{2}t - \frac{5}{2}t \\ = -\frac{1}{2}t \end{array} \right.$$

(4) So:

$$\cos(2t) + \cos(3t)$$

$$= 2 \cos\left(\frac{5}{2}t\right) \cos\left(-\frac{1}{2}t\right)$$

$$= \boxed{2 \cos\left(\frac{5t}{2}\right) \cos\left(\frac{t}{2}\right)}$$

(b)  $\cos(2t) + \sin(3t)$ . Hint:  $\cos(z) = \sin(z + \pi/2)$  and  $\sin(z) = \cos(z - \pi/2)$ .

$$\begin{aligned} \textcircled{1} \quad &= \cos(2t) + \cos\left(3t - \frac{\pi}{2}\right) \\ \cos(\alpha + \beta) + \cos(\alpha - \beta) &= 2 \cos \alpha \cos \beta \end{aligned}$$

$$\alpha + \beta = 2t$$

$$\alpha - \beta = 3t - \frac{\pi}{2}$$

$$\hline 2\alpha = 5t - \frac{\pi}{2}$$

$$\alpha = \frac{5}{2}t - \frac{\pi}{4}$$

$$\begin{aligned} \beta &= 2t - \alpha = 2t - \left(\frac{5}{2}t - \frac{\pi}{4}\right) \\ &= -\frac{1}{2}t + \frac{\pi}{4} \end{aligned}$$

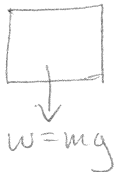
$$\textcircled{2} \quad \text{So } \cos(2t) + \sin(3t)$$

$$= \boxed{2 \cos\left(\frac{5}{2}t - \frac{\pi}{4}\right) \cos\left(-\frac{1}{2}t + \frac{\pi}{4}\right)}$$

$$= \boxed{2 \cos\left(\frac{5}{2}t - \frac{\pi}{4}\right) \cos\left(\frac{t}{2} - \frac{\pi}{4}\right)}$$

2. [3.8.9] An undamped spring-mass system with a mass that weighs 6 lb and a spring constant of 1 lb/in is suddenly set in motion at  $t = 0$  by an external force of  $4 \cos 7t$  lb. Determine the position of the mass  $u(t)$  (in) at time  $t$  (s), expressing  $u(t) = u_c(t) + U(t)$ , where  $u_c(t)$  is the transient solution and the steady state solution  $U(t)$  is expressed as a product of two trigonometric functions. Units: m, s; force: lb.

$$\textcircled{1} \quad mu'' + \gamma u' + ku = 4 \cos 7t$$



$$6 \text{ lb} = m \cdot 32 \frac{\text{ft}}{\text{s}^2}$$

$$6 \text{ lb} = M \cdot 32 \frac{\text{ft}}{\text{s}^2} \cdot \frac{12 \text{ in}}{\text{ft}}$$

$$M = \frac{6}{32 \cdot 12} \frac{\text{lb s}^2}{\text{in}}$$

$$= \frac{1}{64} \frac{\text{lb s}^2}{\text{in}}$$

$\gamma = 0$  (undamped)

$$k = 1 \frac{\text{lb}}{\text{in}}$$

$$\frac{1}{64} u'' + u = 4 \cos 7t, \quad u(0) = 0, \quad u'(0) = 0$$

$\textcircled{2}$  Transient Soln:

$$\frac{1}{64} r^2 + 1 = 0$$

$$r^2 = -64$$

$$r = \pm 8i$$

$$u_c(t) = c_1 \cos(8t) + c_2 \sin(8t)$$

$\textcircled{3}$  Steady state:

$$[u(t) = A \cos(7t) + B \sin(7t)] \cdot 1$$

$$[u'(t) = 7B \cos(7t) - 7A \sin(7t)] \cdot 0$$

$$[u''(t) = -49A \cos(7t) - 49B \sin(7t)] \cdot \frac{1}{64}$$

$$(A - \frac{49}{64}A) \cos(7t) + (B - \frac{49}{64}B) \sin(7t) = 4 \cos(7t)$$

$$A - \frac{49}{64}A = 4; \quad B - \frac{49}{64}B = 0$$

$$\frac{15}{64}A = 4$$

$$A = \frac{256}{15}$$

$$B = 0$$

$$\textcircled{4} \quad u(t) = c_1 \cos(8t) + c_2 \sin(8t) + \frac{256}{15} \cos(7t)$$

$$u(0) = 0: \quad 0 = c_1 + 0 + \frac{256}{15}, \quad c_1 = -\frac{256}{15}$$

$$u'(t) = -8c_1 \sin(8t) + 8c_2 \cos(8t) - \frac{256 \cdot 7}{15} \sin(7t)$$

$$u'(0) = 0: \quad 0 = 0 + 8c_2 + 0, \quad c_2 = 0$$

$$\textcircled{5} \quad u(t) = \frac{256}{15} (\cos(7t) - \cos(8t))$$

$$\cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$$

$$-\cos(\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta$$

$$\cos(\alpha + \beta) - \cos(\alpha - \beta) = -2 \sin \alpha \sin \beta$$

$$\cos(\alpha - \beta) - \cos(\alpha + \beta) = 2 \sin \alpha \sin \beta$$

$$\alpha - \beta = 7t$$

$$\beta = 8t - \alpha$$

$$\alpha + \beta = 8t$$

$$= \frac{16}{2}t - \frac{15}{2}t$$

$$2\alpha = 15t$$

$$= \frac{1}{2}t$$

$$\alpha = \frac{15}{2}t$$

$$u(t) = \frac{256}{15} \left[ 2 \sin\left(\frac{15}{2}t\right) \sin\left(\frac{1}{2}t\right) \right]$$

$$u(t) = \frac{512}{15} \sin\left(\frac{15}{2}t\right) \sin\left(\frac{1}{2}t\right)$$

3. Now, modify the system in #2 so that the damping constant is  $\gamma = 11 \text{ lb} \cdot \text{s/in}$ . Find the forced response  $U(t)$ , expressed in the form  $U(t) = R \cos(7t)$ . How does this compare with the static response? Is this system demonstrating resonance?

$$\textcircled{1} \quad \frac{1}{64} u'' + u' + u = 4 \cos(7t)$$

$$\textcircled{2} \quad \frac{1}{64} r^2 + r + 1 = 0$$

$$r = \frac{-1 \pm \sqrt{1 - 4 \cdot \frac{1}{64} \cdot 1}}{\frac{1}{32}}$$

$$= -32 \pm 32 \sqrt{1 - \frac{1}{16}}$$

$$= -32 \pm 8\sqrt{15} \quad \leftarrow \text{Notice: no } i \text{ here!}$$

~~$$u(t) = c_1 e^{-62.98t} + c_2 e^{-1.02t}$$~~

$$u(t) = c_1 e^{-62.98t} + c_2 e^{-1.02t} \quad \leftarrow \text{over damped system.}$$

$$\textcircled{3} \quad [U(t) = A \cos(7t) + B \sin(7t)] \cdot 1$$

$$[U'(t) = 7B \cos(7t) - 7A \sin(7t)] \cdot 1$$

$$[U''(t) = -49A \cos(7t) - 49B \sin(7t)] \cdot \frac{1}{64}$$

$$\left[ \left(1 - \frac{49}{64}\right)A + 7B \right] \cos(7t) + \left[ \left(1 - \frac{49}{64}\right)B - 7A \right] \sin(7t) = 4 \cos(7t)$$

$$\frac{15}{64}A + 7B = 4$$

$$-7A + \frac{15}{64}B = 0$$

$$7A + \frac{7 \cdot 64}{15}B = \frac{4 \cdot 7 \cdot 64}{15}$$

$$B \approx 0.5708$$

$$A \approx 0.0191$$

$$\begin{aligned} \textcircled{4} \quad U(t) &\approx 0.0191 \cos(7t) + 0.5708 \sin(7t) \\ &= R \cos(7t - \delta) \end{aligned}$$

$$R = \sqrt{A^2 + B^2} \approx 0.5711$$

$$\delta = \tan^{-1}\left(\frac{B}{A}\right) \approx 1.5373$$

$$U(t) = 0.5711 \cos(7t - 1.5373)$$

The forced response has amplitude 0.5711 in.

The static response is

$$\frac{F}{k} = \frac{4 \text{ lb}}{1 \text{ lb/in}} = 4 \text{ in.}$$

So, the forced response is much smaller than the static response.

The system is not demonstrating resonance.

Alternatively:

$$\Gamma = \frac{\gamma^2}{mk} = \frac{11^2}{\frac{1}{64} \cdot 1} = 64$$

Since  $\Gamma \geq 2$ , the system is too damped to experience resonance.