

Name: Selcham1. [3 parts, 2 points each] A spring/mass system is modeled by $6u'' + 7u' + 2u = \cos(\omega t)$.

- (a) Compute the normalized damping constant. Is the system overdamped, critically damped, or neither?

$$\Gamma = \frac{\gamma^2}{mk} = \frac{7^2}{6 \cdot 2} = \frac{49}{12} = \frac{48}{12} + \frac{1}{12} = \boxed{4 + \frac{1}{12}}. \quad \text{Since } \Gamma > 4,$$

the system is overdamped.

- (b) Compute the steady-state response
- $U(t)$
- . (Hint: use Cramer's Rule to simplify the process of solving the system of equations.)

• $\gamma > 0 \Rightarrow$ transient soln
dies out \Rightarrow no conflict
with the family:

$\cos(\omega t)$
|
 $\omega \sin(\omega t)$
|
 ~~$\omega \cos(\omega t)$~~ repeat.

- $U(t) = A \cos(\omega t) + B \sin(\omega t)$
- $U' = -\omega B \cos(\omega t) - \omega A \sin(\omega t)$
- $U'' = \omega^2 A \cos(\omega t) - \omega^2 B \sin(\omega t)$

$$6u'' + 7u' + 2u = \begin{pmatrix} -6\omega^2 A + 7\omega B + 2A \\ -6\omega^2 B - 7\omega A + 2B \end{pmatrix} \begin{pmatrix} \cos(\omega t) \\ \sin(\omega t) \end{pmatrix}$$

$$\begin{cases} (-6\omega^2 + 2)A + 7\omega B = 1 \\ -7\omega A + (2 - 6\omega^2)B = 0 \end{cases}$$

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$$\underbrace{\begin{bmatrix} 2-6\omega^2 & 7\omega \\ -7\omega & 2-6\omega^2 \end{bmatrix}}_M \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\det(M) = (2-6\omega^2)^2 + 49\omega^2 = 4\omega^4 + 36\omega^4 + 49\omega^2 = 36\omega^4 + 25\omega^2 + 4$$

$$A = \frac{\begin{vmatrix} 1 & 7\omega \\ 0 & 2-6\omega^2 \end{vmatrix}}{\det(M)} = \frac{2-6\omega^2}{36\omega^4 + 25\omega^2 + 4} \quad B = \frac{\begin{vmatrix} 2-6\omega^2 & 1 \\ -7\omega & 0 \end{vmatrix}}{\det(M)} = \frac{7\omega}{36\omega^4 + 25\omega^2 + 4}$$

(c) Using part (b), compute the amplitude R of the steady-state in terms of ω .

$$U(t) = \frac{2-6\omega^2}{36\omega^4 + 25\omega^2 + 4} \cos(\omega t) + \frac{7\omega}{36\omega^4 + 25\omega^2 + 4} \sin(\omega t)$$

$$(c) \quad R = \sqrt{A^2 + B^2} = \left(\frac{(2-6\omega^2)^2 + (7\omega)^2}{(36\omega^4 + 25\omega^2 + 4)^2} \right)^{\frac{1}{2}} = \left(\frac{36\omega^4 + 25\omega^2 + 4}{(36\omega^4 + 25\omega^2 + 4)^2} \right)^{\frac{1}{2}}$$

$$= \frac{1}{\sqrt{36\omega^4 + 25\omega^2 + 4}}$$

2. [2 parts, 2 points each] Trig sums.

(a) Express $\sin(3t) + \sin(4t)$ as the product of two trigonometric functions.

$$\sin(\alpha + \beta) = \sin(\alpha)\cos(\beta) + \cos(\alpha)\sin(\beta)$$

$$\sin(\alpha - \beta) = \sin(\alpha)\cos(\beta) - \cos(\alpha)\sin(\beta)$$

$$\sin(\alpha + \beta) + \sin(\alpha - \beta) = 2\sin(\alpha)\cos(\beta)$$

$$\sin(3t) + \sin(4t) = 2\sin\left(\frac{7}{2}t\right)\cos\left(-\frac{1}{2}t\right)$$

$$= \boxed{2\sin\left(\frac{7}{2}t\right)\cos\left(\frac{1}{2}t\right)}$$

$$\alpha + \beta = 3t \quad \alpha + \beta = 3t$$

$$\alpha - \beta = 4t \quad -(\alpha - \beta = 4t)$$

$$2\alpha = 7t \quad 2\beta = -t$$

$$\alpha = \frac{7}{2}t \quad \beta = -\frac{1}{2}t$$

(b) Determine all real solutions t to $\sin(3t) + \sin(4t) = 0$.

$$2\sin\left(\frac{7}{2}t\right)\cos\left(\frac{1}{2}t\right) = 0$$

$$2 \neq 0 \quad \text{or } \sin\left(\frac{7}{2}t\right) = 0 \quad \text{or } \cos\left(\frac{1}{2}t\right) = 0$$

$$\bullet \frac{7}{2}t = k\pi$$

for some integer k

$$t = \frac{2\pi}{7} \cdot k \text{ for some integer } k$$

$$\frac{1}{2}t = \frac{\pi}{2} + k\pi \quad \text{for some integer } k$$

$$t = \pi + 2\pi k$$

$$= \pi(2k+1) \quad \text{for some integer } k$$

Solus: $t = \dots, -2 \cdot \frac{2\pi}{7}, -1 \cdot \frac{2\pi}{7}, 0, 1 \cdot \frac{2\pi}{7}, 2 \cdot \frac{2\pi}{7}, \dots$

or $t = \dots, -5\pi, -3\pi, -\pi, \pi, 3\pi, 5\pi, \dots$