EXAM 4 -A1 MATH 261: Elementary Differential Equations MATH 261
FALL 2009 EXAMINATION COVER PAGE Professor Moseley

PRINT NAME____(________________________)
Last Name, First Name MI (What you wish to be called)

ID # ____ EXAM DATE Friday, Nov. 19, 2009 11:30 am

I swear and/or affirm that all of the work presented on this exam is my own and that I have neither given nor received any help during the exam.

________________________________ ________________
SIGNATURE DATE

Date _______ Signature_____

INSTRUCTIONS: Besides this cover page, there are 11 pages of questions and problems on this exam. **MAKE SURE YOU HAVE ALL THE PAGES**. If a page is missing, you will receive a grade of zero for that page. Page 12 contains Laplace transforms you need not memorize. Read through the entire exam. If you cannot read anything, raise your hand and I will come to you. Place your I.D. on your desk during the exam. Your I.D., this exam, and a straight edge are all that you may have on your desk during the exam. **NO CALCULATORS! NO SCRATCH PAPER!** Use the back of the exam sheets if necessary. You may remove the staple if you wish. Print your name on all sheets. Pages 1-11 are Fill-in-the Blank/Multiple Choice or True/False. Expect no part credit on these pages. For each Fill-in-the Blank/Multiple Choice question write your answer in the blank provided. Next find your answer from the list given and write the corresponding letter or letters for your answer in the blank provided. Then circle this letter or letters. There are no free response pages. However, to insure credit, you should explain your solutions fully and carefully. Your entire solution may be graded, not just your final answer. **SHOW YOUR WORK!** Every thought you have should be expressed in your best mathematics on this paper. Partial credit will be given as deemed appropriate. Proofread your solutions and check your computations as time allows. GOOD LUCK!!

Scores

page	points	score
1	11	
2	5	
3	12	
4	17	
5	12	
6	6	
7	8	
8	4	
9	12	
10	6	
11	7	
12	---	
13		
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22		

REQUEST FOR REGRADE

Please regrade the following problems for the reasons I have indicated: (e.g., I do not understand what I did wrong on page ____.)

(Regrades should be requested within a week of the date the exam is returned. Attach additional sheets as necessary to explain your reasons.) I swear and/or affirm that upon the return of this exam I have **written nothing on this exam** except on this REGRADE FORM. (Writing or changing anything is considered to be cheating.)

Total	100	

MATH 261 EXAM 4A-1 Prof. Moseley

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True-false. Laplace transforms.

1. (1 pts) A)True or B)False The definition of the Laplace transform is $\mathcal{L}\{f(t)\}(s) = \int_{t=0}^{t=\infty} f(t)e^{-t}dt$ provided the improper integral exists.

2. (1 pts) A)True or B) False Since the Laplace transform is defined in terms of an improper integral, it involves two limit processes.

3. (1 pts) A)True or B)False The Laplace transform exists for some continuous functions on $[0,\infty)$.

4. (1 pts) A)True or B)False The Laplace transform does exists for some discontinuous functions.

5. (1 pts) A)True or B)False The function f(t) = 1/(t-3) is not piecewise continuous on [0,7].

6. (1 pts) A)True or B)False The function $f(t) = e^{4t^2}\cos(t)$ is not of exponential order.

7. (1 pts) A)True or B)False The Laplace transform $\mathcal{L}$:**T**→**F** is not a linear operator.

8. (1 pts) A)True or B)False The inverse Laplace transform $\mathcal{L}^{-1}$:**F**→**T** is not a linear operator.

9. (1 pts) A)True or B)False The Laplace transform is not a one-to-one mapping on the set of continuous functions on $[0,\infty)$ for which the Laplace transform exists.

10. (1 pts) A)True or B)False There is more than one continuous function in the null space of $\mathcal{L}$.

11. (1 pts) A)True or B)False The strategy of solving an ODE using Laplace transforms is not to transform the problem from the time domain **T** to the (complex) frequency domain **F**, solve the transformed problem using algebra instead of calculus, and then transform the solution back to the time domain **T**.

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions. Also, circle your answer.

12. (5 pts.) The Laplace transform of the function $f(t) = \begin{cases} 8 & 0 \le t \le 5 \\ 0 & t > 5 \end{cases}$

is ____. _____A B C D E

Hint: Use the definition. Be careful to handle the limit appropriately as discussed in class.

A) $\frac{8}{s}$ B) $\frac{-8}{s}$ C) $\frac{8}{s}e^{-5s}$ D) $\frac{-8}{s}e^{-5s}$ E) $\frac{8}{s}(1+e^{-5s})$ AB) $\frac{8}{s}(1-e^{-5s})$ AC) $\frac{8}{s}(e^{-5s}-1)$

AD) $\frac{5}{s}$ AE) $\frac{-5}{s}$ BC) $\frac{5}{s}e^{-8s}$ BD) $\frac{-5}{s}e^{-8s}$ BE) $\frac{5}{s}(1+e^{-8s})$ CD) $\frac{5}{s}(1-e^{-8s})$

CE) $\frac{5}{s}(e^{-8s}-1)$ ABC) $\frac{5}{s}(1-e^{8s})$ ABCDE) None of the above.

Total points this page = 5. TOTAL POINTS EARNED THIS PAGE _________

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions.

Compute the Laplace transform of the following functions.

13. (4 pts.) $f(t) = 2t + 3t^2$ $\mathcal{L}(f)$ = __________________________________. ______ A B C D E

14. (4 pts.) $f(t) = 2\,e^{2t} - 3\,e^{-3t}$ $\mathcal{L}(f)$ = ______________________________. ______ A B C D E

15 (4 pts.) $f(t) = 2\sin(2t) - 3\cos(3t)$ $\mathcal{L}(f)$ = ________________________. ______ A B C D E

Possible answers this page

A) $\frac{2}{s}+\frac{3}{s^2}$ B) $\frac{2}{s}-\frac{3}{s^2}$ C) $-\frac{2}{s}+\frac{3}{s^2}$ D) $-\frac{2}{s}-\frac{3}{s^2}$ E) $\frac{2}{s^2}+\frac{6}{s^3}$ AB) $\frac{2}{s^2}-\frac{6}{s^3}$ AC) $-\frac{2}{s^2}+\frac{6}{s^3}$ AD) $-\frac{2}{s^2}-\frac{6}{s^3}$

AE) $\frac{2}{s+2}+\frac{3}{s+3}$ BC) $\frac{2}{s+2}-\frac{3}{s+3}$ BD) $-\frac{2}{s+2}+\frac{3}{s+3}$ BE) $-\frac{2}{s+2}-\frac{3}{s+3}$

CD) $\frac{2}{s-2}+\frac{3}{s+3}$ CE) $\frac{2}{s-2}-\frac{3}{s+3}$ DE) $-\frac{2}{s-2}+\frac{3}{s+3}$ ABC) $-\frac{2}{s-2}-\frac{3}{s+3}$

ABD) $\frac{4}{s^2+4}+\frac{3s}{s^2+9}$ ABE) $\frac{4}{s^2+4}-\frac{3s}{s^2+9}$ ACD) $-\frac{4}{s^2+4}+\frac{3s}{s^2+9}$ ACE) $-\frac{4}{s^2+4}-\frac{3s}{s^2+9}$

ADE) $\frac{4}{s^2-4}+\frac{3s}{s^2-9}$ BCD) $\frac{4}{s^2-4}-\frac{3s}{s^2-9}$ BDE) $-\frac{4}{s^2-4}+\frac{3s}{s^2-9}$ CDE) $-\frac{4}{s^2-4}-\frac{3s}{s^2-9}$

ABCD) $-\frac{2}{(s-2)^2}+\frac{3}{(s+3)^2}$ ABCE) $\frac{2}{s^2+2}+\frac{3s}{s^2+3}$ ABDE) $\frac{2s}{s^2+2}+\frac{3}{s^2+3}$
ACDE) $\mathcal{L}\{f\}$ exists but none of the above is $\mathcal{L}\{f\}$ BCDE) $\mathcal{L}\{f\}$ does not exist.
ABCDE)None of the above.
Total points this page = 12. TOTAL POINTS EARNED THIS PAGE ________

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions.

DEFINITION. Let f:X→Y. Then f is one-to-one if $\forall$ x_1, $x_2 \in X$ we have

16.(2 pts.) ____________ ____ A B C D E implies 17(2pt) ________________ ____ A B C D E

THEOREM. Let T:V→W be a linear operator where V and W are vector spaces over the same field **K**. If the null space N_T contains only the zeo vector, then T is a one-to-one mapping.

Proof. We begin our proof of the theorem by first proving the following lemma:

Lemma. Let T:V→W be a linear operator and N_T = $\{\vec{0}\}$. If $T(\vec{v}_1)=\vec{0}$, then $\vec{v}_1=\vec{0}$.

Proof of lemma: Let T:V→W be a linear operator, N_T = $\{\vec{0}\}$ and $T(\vec{v}_1)=\vec{0}$. By the definition

of the null space we have that N_T = { $\vec{v}$ ∈V: 18.(2 pt.) _______________ _____ A B C D E} so that $T(\vec{v}_1)=\vec{0}$

implies that $\vec{v}_1 \in N_T$. Since N_T contains 19.(1 pt.) _______________________ ______ A B C D E, we have that $\vec{v}_1=\vec{0}$ as was to be proved. QED for lemma.

Having finished the proof of the lemma, we now finish the proof of the theorem. To show that T

is one-to-one, for $\vec{v}_1,\vec{v}_2 \in V$ we assume 20.(1 pt.) __________________ _____A B C D E

and show that 21.(1 pt.) __________________. _____A B C D E. We use the STATEMENT/REASON format.

STATEMENT	REASON
$T(\vec{v}_1)=T(\vec{v}_2)$	22.(2 pt.) __________________ _____ A B C D E
23.(2pt.) ____________ ___ A B C D E	Vector algebra in W
$T(\vec{v}_1-\vec{v}_2)=\vec{0}$	24.(2 pt.) __________________ _____ A B C D E
$\vec{v}_1-\vec{v}_2=\vec{0}$	25.(2 pt.) __________________ ______ A B C D E
$\vec{v}_1=\vec{v}_2$	Vector algebra in V

Hence T is one-to-one as was to be proved. QED for the theorem.

Possible answers for this page: A)$x_1 = x_2$ B)$x_1 + x_2 = 0$ C) $f(x_1+ x_2) = 0$ D) $f(x_1) = f(x_2)$
E) $f(x_1) + f(x_2) =0$ AB)$T(\vec{v}_1) = \vec{0}$ AC) $T(\alpha\vec{v}_1) = \alpha T(\vec{v}_1)$ AD) $T(\vec{v}) = \vec{0}$ AE)$T(\vec{v}_1)=T(\vec{v}_2)$
BC) Hypothesis (or Given) BD) only the zero vector BE) The lemma proved above

CD) Vector algebra in V CE) Vector algebra in W DE) only the vector $\vec{v}_1$ ABC) $\vec{v}_1 = \vec{v}_2$
ABD) $T(\vec{v}_1 - \vec{v}_2)$ ABE) $T(\vec{v}_1 + \vec{v}_2) = \vec{0}$ BCD) $T(\vec{v}_2) = \vec{0}$ BCE) $\vec{v}_1 = \vec{0}$ BDE) T is a one-to-one mapping CDE) T is a linear operator ABCD) Definition of T ABCE) Theorems from Calculus
ACDE) Definition of f ABCDE) None of the above.
Total points this page = 17. TOTAL POINTS EARNED THIS PAGE ________

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions.

Compute the inverse Laplace transform of the following functions.

26. (4 pts.) $F(s) = \frac{2}{s} - \frac{3}{s+2}$ $\mathcal{L}^{-1}\{F\}$ = ____________________________. _____ A B C D E

27. (4 pts.) $F(s) = \frac{2s-4}{s^2+9}$ $\mathcal{L}^{-1}\{F\}$ = ________________________________. _____ A B C D E

28. (4 pts.) $F(s) = \frac{2s-3}{s^2-2s+2}$ $\mathcal{L}^{-1}\{F\}$ = ______________________________. _____ A B C D E

Possible answers this page
A) $2 + 3e^{2t}$ B) $2 - 3e^{2t}$ C) $-2 + 3e^{2t}$ D) $-2 - 3e^{2t}$ E) $2 + 3e^{-2t}$ AB) $2 - 3e^{-2t}$ AC) $-2 + 3e^{-2t}$
AD) $-2 - 3e^{-2t}$ AE) $2\cos 3t + 4\sin 3t$ BC) $2\cos 3t - 4\sin 3t$ AD) $-2\cos 3t + 4\sin 3t$

AE) $-2 \cos 3t - 4 \sin 3t$ BC) $2 \cos t + (4/3) \sin 3t$ BC) $2 \cos 3t - (4/3) \sin 3t$
AD) $-2 \cos 3t + (4/3) \sin 3t$ AE) $-2 \cos 3t - (4/3) \sin 3t$ BD) $2e^t \cos t + 5e^t \sin t$
BE) $2e^t \cos t - 5e^t \sin t$ CD) $-2e^t \cos t + 5e^t \sin t$ CE) $-2e^t \cos t - 5e^t \sin t$
BD) $2e^t \cos t + e^t \sin t$ BE) $2e^t \cos t - e^t \sin t$ CD) $-2e^t \cos t + e^t \sin t$
CE) $-2e^t \cos t - e^t \sin t$ ACDE) $\mathcal{L}^{-1}\{f\}$ exists but none of the above is $\mathcal{L}\{f\}$
BCDE) $\mathcal{L}^{-1}\{f\}$ does not exist. ABCDE) None of the above.

Total points this page = 12. TOTAL POINTS EARNED THIS PAGE ________

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Answer questions using the instructions on the Exam Cover Sheet. Also, circle your answer.

Consider the IVP: ODE $y'' + 4y = 0$ IC's: $y(0) = 3$, $y'(0) = 2$

Let $Y = \mathcal{L}\{y(t)\}(s)$.

29. (3 pts.) As discussed in class (attendance is mandatory), taking the Laplace transform of the ODE and using the initial conditions we may

obtain ____. ______A B C D E

Be careful, if you miss this question, you will also miss the next question.

A) $s^2Y + 2s + 3 + 4Y = 0$ B) $s^2Y + 2s - 3 + 4Y = 0$ C) $s^2Y - 2s + 3 + 4Y = 0$
D) $s^2Y - 2s - 3 - 4Y = 0$ E) $s^2Y + 3s + 2 - 4Y = 0$ AB) $s^2Y + 3s - 2 - 4Y = 0$
AC) $s^2Y - 3s + 2 - 4Y = 0$ AD) $s^2Y - 3s - 2 - 4Y = 0$ AE) $s^2Y - 2s + 4Y = 0$
BC) $s^2Y - s - 3 + 4Y = 0$ BD) None of the above

30. (3 pts.) The Laplace transform of the solution to the IVP

is Y = ____. _____ A B C D E

A) $\frac{2s+3}{s^2+4}$ B) $\frac{2s-3}{s^2+4}$ C) $\frac{-2s+3}{s^2+4}$ D) $-\frac{2s+3}{s^2+4}$ E) $\frac{2s+3}{s^2-4}$ AB) $\frac{2s-3}{s^2-4}$
AC) $\frac{-2s+3}{s^2-4}$ AD) $-\frac{2s+3}{s^2-4}$ AE) $-\frac{2s}{s^2+4}$ BC) $\frac{3s-2}{s^2+4}$ BD) None of the above

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Answer questions using the instructions on the Exam Cover Sheet. Also, circle your answer.

31. (4 pts.) Let S = $\{\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_n\} \subseteq V$ where V is a vector space and (*) be the vector equation $c_1\vec{v}_1 + c_2\vec{v}_2 + \ldots + c_n\vec{v}_n = \vec{0}$. Choose the correct completion of the following:

Definition. The set S is linearly independent

if ____. _____A B C D E

A) (*) has only the solution $c_1 = c_2 = \cdots = c_n = 0$. B) (*) has an infinite number of solutions.
C) (*) has a solution other than the trivial solution. D) (*) has at least two solutions.
E) (*) has no solution. AB) the associated matrix is nonsingular.
AC) the associated matrix is singular. AD) None of the above

32. (4 pts.)Now let $S_1 = \{ [x_1(t), y_1(t), z_1(t)]^T, [x_2(t), y_2(t), z_2(t)]^T, \ldots, [x_n(t), y_n(t), z_n(t)]^T \} \subseteq \vec{\mathcal{A}}(\mathbf{R},\mathbf{R}^3)$ and (**) be the "vector" equation

$c_1 [x_1(t), y_1(t), z_1(t)]^T + c_2 [x_2(t), y_2(t), z_2(t)]^T + \cdots + c_n [x_n(t), y_n(t), z_n(t)]^T = [0, 0, 0]^T \ \forall t \in \mathbf{R}$

Apply the definition above to the space of time varying "vectors" $\vec{\mathcal{A}}(\mathbf{R},\mathbf{R}^3)$. That is, by the definition above the set $S_1 \subseteq \vec{\mathcal{A}}(\mathbf{R},\mathbf{R}^3)$ is linearly independent

if ____. ______ A B C D E

A) (**) has only the solution $c_1 = c_2 = \cdots = c_n = 0$. B) (**) has an infinite number of solutions
C) (**) has a solution other than the trivial solution. D) (**) has at least two solutions.
E) (**) has no solution. AB) the associated matrix is nonsingular.
AC) the associated matrix is singular. AD) None of the above

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33. (4 pts.) You are to determine Directly Using the Definition (DUD) if the following set of time varying "vectors" are linearly independent. Let S = $\{\vec{x}_1(t), \vec{x}_2(t)\} \subseteq \mathcal{A}(\mathbf{R},\mathbf{R}^2)$ where

$$\vec{x}_1(t) = \begin{bmatrix} 3e^t \\ 4e^t \end{bmatrix} \quad \text{and} \quad \vec{x}_2(t) = \begin{bmatrix} 6e^t \\ 9e^{-t} \end{bmatrix}. \quad \text{Then S}$$

is ____. _____ A B C D E

A) linearly independent as $c_1\,\vec{x}_1(t) + c_2\,\vec{x}_2(t) = [0,0]^T \;\; \forall t\in\mathbf{R}$ implies $c_1 = c_2 = 0$.

B)) linearly dependent as $c_1\vec{x}_1(t) + c_2\vec{x}_2(t) = [0,0]^T \;\; \forall t\in\mathbf{R}$ implies $c_1 = c_2 = 0$.

C) linearly independent as $-2\,\vec{x}_1(t) + \vec{x}_2(t) = [0,0]^T \;\; \forall t\in\mathbf{R}$.

D) linearly dependent as $-2\,\vec{x}_1(t) + \vec{x}_2(t) = [0,0]^T \;\; \forall t\in\mathbf{R}$.

E) linearly independent as the associated matrix is nonsingular.

D) linearly dependent as the associated matrix is nonsingular

AB) linearly independent as the associated matrix is singular.

AC) linearly dependent as the associated matrix is singular.

AD) neither linearly independent or linearly dependent as the definition does not apply.

ABCDE) None of the above statements are true.

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Using the procedure illustrated in class (attendance is mandatory), find the eigenvalues of

A = $\begin{bmatrix} i & 4 \\ 0 & 1 \end{bmatrix} \in \mathbf{C}^{2x2}$.

34. (4 pts.) A polynomial p(λ) where solving p(λ) = 0 yields the eigenvalues of A can be written

as p(λ) =____. ______ A B C D E

A) (i+λ)(1+λ) B) (i+λ)(1−λ) C) (i−λ)(1+λ) D) (i−λ)(1−λ) E) (i+λ)(2+λ) AB) (i+λ)(2−λ) AC) (i−λ)(2+λ) AD)(i−λ)(2−λ) AE) (2i+λ)(1+λ) BC)(2i+λ)(1−λ) BD)(2i−λ)(1+λ) BE) (2i−λ)(1−λ) CD) (2i+λ)(2+λ) CE)(2i+λ)(2−λ) DE)(2i−λ)(2+λ) ABC)(2i−λ)(2−λ) ABD) (3i−λ)(2+λ) ABE)None of the above.

35. (2 pt.) The degree of p(λ) is __________. ______ A B C D E A) 1 B) 2 C) 3 D) 4 E) 5 AB) 6 AC) 7 AD) None of the above.

36. (2 pt.) Counting repeated roots, the number of eigenvalues of A

is _________. _____ A B C D E A) 0 B) 1 C) 2 D) 3 E) 4 AB) 5 AC) 6 AD) 7 AE) 8 BC) None of the above

37. (4 pts.) The eigenvalues of A can be written as ______________________._____ A B C D E

A) $\lambda_1 = 1, \lambda_2 = i$ B) $\lambda_1 = 1, \lambda_2 = -i$ C) $\lambda_1 = -1, \lambda_2 = i$ D) $\lambda_1 = -1, \lambda_2 = -i$ E) $\lambda_1 = 2, \lambda_2 = i$ AB) $\lambda_1 = 2, \lambda_2 = -i$ AC) $\lambda_1 = -2, \lambda_2 = i$ AD) $\lambda_1 = -2, \lambda_2 = -i$ AE) $\lambda_1 = 1, \lambda_2 = 2i$ BC) $\lambda_1 = 1, \lambda_2 = -2i$ BD) $\lambda_1 = -1, \lambda_2 = 2i$ BE) $\lambda_1 = -1, \lambda_2 = -2i$ CD) $\lambda_1 = 2, \lambda_2 = 2i$ CE) $\lambda_1 = 2, \lambda_2 = -2i$ DE) $\lambda_1 = -2, \lambda_2 = 2i$ ABC) $\lambda_1 = -2, \lambda_2 = -2i$ ABD) None of the above

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions. Also, circle your answer.

Note that $\lambda_1 = 2$ is an eigenvalue of the matrix $A = \begin{bmatrix} 3 & -1 \\ 4 & -2 \end{bmatrix}$

38. (5 pts.) Using the conventions discussed in class (attendance is mandatory), a basis B for

the eigenspace associated with λ_1 is B = ___________________. ___A B C D E

A) $\{[1,1]^T, [4,4]^T\}$ B) $\{[1,1]^T\}$ C) $\{[1,2]^T\}$ D) $\{[1,2]^T, [4,8]^T\}$ E) $\{[2,1]^T\}$
AB) $\{[1,3]^T\}$ AC) $\{[1,4]^T\}$ AD) $\{[4,1]^T\}$ AE) $\{[3,1]^T\}$ BC) $\{[1,-1]^T, [4,4]^T\}$
BD) $\{[1,-1]^T\}$ BE) $\{[1,-2]^T\}$ CD) $\{[1,-2]^T, [4,8]^T\}$ CE) $\{[2,1]^T\}$ DE) $\{[1,3]^T\}$
ABC) $\{[1,-4]^T\}$ ABD) $\{[4,-1]^T\}$ ABE) $\{[3,-1]^T\}$
ACD) $\lambda = 2$ is not an eigenvalue of the matrix A
ACE) $\lambda = -1$ is not an eigenvalue of the matrix A
ADE) $\lambda = 3$ is not an eigenvalue of the matrix A ABCDE) None of the above is correct.

39. (1pt.) Although there are an infinite number of eigenvectors associated with any eigenvalue, the eigenspace associated with λ_1 is often one dimensional. Hence conventions for selecting eigenvector(s) associated with λ_1 have been developed (by engineers). We say that the eigenvector(s) associated with λ_1

is (are) ________________________________. ______A B C D E

A) $[1,1]^T, [4,4]^T$ B) $[1,1]^T$ C) $\{[1,2]^T\}$ D) $[1,2]^T, [4,8]^T$ E) $[2,1]^T$
AB) $[1,3]^T$ AC) $[1,4]^T$ AD) $[4,1]^T$ AE) $[3,1]^T$ BC) $[1,-1]^T, [4,4]^T$
BD) $[1,-1]^T$ BE) $[1,-2]^T$ CD) $[1,-2]^T, [4,8]^T$ CE) $[2,1]^T$ DE) $[1,3]^T$
ABC) $[1,-4]^T$ ABD) $[4,-1]^T$ ABE) $[3,-1]^T$
ACD) $\lambda_1 = 2$ is not an eigenvalue of the matrix A
ACE) $\lambda_1 = -1$ is not an eigenvalue of the matrix A
ADE) $\lambda = 3$ is not an eigenvalue of the matrix A ABCDE) None of the above is correct.

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Answer questions using the instructions on the Exam Cover Sheet. Also, circle your answer.

Let the 2x2 matrix A have the eigenvalue table

Let L:$\mathcal{A}(\mathbf{R},\mathbf{R}^2)\to\mathcal{A}(\mathbf{R},\mathbf{R}^2)$ be defined by $L[\vec{x}] = \vec{x}' - A\vec{x}$

and let the null space of L be N_L

TABLE

Eigenvalues	Eigenvectors
$r_1 = 1$	$\vec{\xi}_1 = \begin{bmatrix}1\\2\end{bmatrix}$
$r_2 = 2$	$\vec{\xi}_2 = \begin{bmatrix}2\\1\end{bmatrix}$

40. (2 pt). The dimension of N_L is ________. _____ A B C D E

A) 0 B) 1 C) 2 D) 3 E) 4 AB) 5 AC) 6 AD) None of the above.

41. (3 pts.) A basis for the null space of L is__________________________ . ____ A B C D E

A) $B=\left\{\begin{bmatrix}2\\1\end{bmatrix}e^{t},\begin{bmatrix}1\\2\end{bmatrix}e^{2t}\right\}$ B) $B=\left\{\begin{bmatrix}2\\1\end{bmatrix}e^{-t},\begin{bmatrix}1\\2\end{bmatrix}e^{2t}\right\}$ C) $B=\left\{\begin{bmatrix}2\\1\end{bmatrix}e^{t},\begin{bmatrix}1\\2\end{bmatrix}e^{-2t}\right\}$ D) $B=\left\{\begin{bmatrix}2\\1\end{bmatrix}e^{-t},\begin{bmatrix}1\\2\end{bmatrix}e^{-2t}\right\}$

E) $B=\left\{\begin{bmatrix}1\\2\end{bmatrix}e^{t},\begin{bmatrix}2\\1\end{bmatrix}e^{2t}\right\}$ AB) $B=\left\{\begin{bmatrix}1\\2\end{bmatrix}e^{-t},\begin{bmatrix}2\\1\end{bmatrix}e^{2t}\right\}$ AC) $B=\left\{\begin{bmatrix}1\\2\end{bmatrix}e^{t},\begin{bmatrix}2\\1\end{bmatrix}e^{-2t}\right\}$ AD) $B=\left\{\begin{bmatrix}1\\2\end{bmatrix}e^{-t},\begin{bmatrix}2\\1\end{bmatrix}e^{-2t}\right\}$ AE) $B=\left\{\begin{bmatrix}1\\2\end{bmatrix}e^{-t},\begin{bmatrix}2\\-1\end{bmatrix}e^{2t}\right\}$ BC) $B=\left\{\begin{bmatrix}1\\-2\end{bmatrix}e^{-t},\begin{bmatrix}2\\1\end{bmatrix}e^{-2t}\right\}$ BD) $B=\left\{\begin{bmatrix}1\\-2\end{bmatrix}e^{-t},\begin{bmatrix}2\\1\end{bmatrix}e^{2t}\right\}$ BE) $B=\left\{\begin{bmatrix}1\\-2\end{bmatrix}e^{-t},\begin{bmatrix}2\\1\end{bmatrix}e^{2t}\right\}$ CD) None of the above

42. (2 pts.) The general solution of $\vec{x}' = A\vec{x}$ is ____________________________. ___ A B C D E

A) $\vec{x}(t)=c_1\begin{bmatrix}2\\1\end{bmatrix}e^{t}+c_2\begin{bmatrix}1\\2\end{bmatrix}e^{2t}$ B) $\vec{x}(t)=c_1\begin{bmatrix}2\\1\end{bmatrix}e^{-t}+c_2\begin{bmatrix}1\\2\end{bmatrix}e^{2t}$ C) $\vec{x}(t)=c_1\begin{bmatrix}2\\1\end{bmatrix}e^{t}+c_2\begin{bmatrix}1\\2\end{bmatrix}e^{-2t}$ D) $\vec{x}(t)=c_1\begin{bmatrix}2\\1\end{bmatrix}e^{-t}+c_2\begin{bmatrix}1\\2\end{bmatrix}e^{-2t}$

E) $\vec{x}(t)=c_1\begin{bmatrix}1\\2\end{bmatrix}e^{t}+c_2\begin{bmatrix}2\\1\end{bmatrix}e^{2t}$ AB) $\vec{x}(t)=c_1\begin{bmatrix}1\\2\end{bmatrix}e^{-t}+c_2\begin{bmatrix}2\\1\end{bmatrix}e^{2t}$ AC) $\vec{x}(t)=c_1\begin{bmatrix}1\\2\end{bmatrix}e^{t}+c_2\begin{bmatrix}2\\1\end{bmatrix}e^{-2t}$ AD) $\vec{x}(t)=c_1\begin{bmatrix}1\\2\end{bmatrix}e^{-t}+c_2\begin{bmatrix}2\\1\end{bmatrix}e^{-2t}$

AE) $\vec{x}(t)=c_1\begin{bmatrix}1\\2\end{bmatrix}e^{-t}+c_2\begin{bmatrix}2\\-1\end{bmatrix}e^{2t}$ BC) $\vec{x}(t)=c_1\begin{bmatrix}1\\-2\end{bmatrix}e^{-t}+c_2\begin{bmatrix}2\\1\end{bmatrix}e^{-2t}$ BD) $\vec{x}(t)=c_1\begin{bmatrix}1\\-2\end{bmatrix}e^{-t}+c_2\begin{bmatrix}2\\1\end{bmatrix}e^{2t}$

BE) $\vec{x}(t)=c_1\begin{bmatrix}1\\-2\end{bmatrix}e^{-t}+c_2\begin{bmatrix}2\\1\end{bmatrix}e^{2t}$ CD)None of the above

Total points this page = 7. TOTAL POINTS EARNED THIS PAGE ____________