

PRINT NAME _____ (_____) ID No. _____
 Last Name, First Name MI, What you wish to be called

True-false. Laplace transforms.

1. (1 pts) A)True or B)False By definition, $\mathcal{L}\{f(t)\}(s) = \int_{t=0}^{t=\infty} f(t)e^{-st}dt$ provided the improper integral exists.
2. (1 pts) A)True or B) False Since the Laplace transform is defined in terms of an improper integral, it involves only one limit process.
3. (1 pts) A)True or B)False The Laplace transform exists for all continuous functions on $[0, \infty)$.
4. (1 pts) A)True or B)False The Laplace transform does not exist for any discontinuous functions.
5. (1 pts) A)True or B)False The function $f(t) = 1/(t-3)$ is piecewise continuous on $[0, 7]$.
6. (1 pts) A)True or B)False The function $f(t) = e^{4t^2} \cos(t)$ is of exponential order.
7. (1 pts) A)True or B)False The Laplace transform $\mathcal{L}:\mathbf{T}\rightarrow\mathbf{F}$ is a linear operator.
8. (1 pts) A)True or B)False The inverse Laplace transform $\mathcal{L}^{-1}:\mathbf{F}\rightarrow\mathbf{T}$ is a linear operator.
9. (1 pts) A)True or B)False The Laplace transform is a one-to-one mapping on the set of continuous functions on $[0, \infty)$ for which the Laplace transform exists.
10. (1 pts) A)True or B)False There is at most one continuous functions in the null space of \mathcal{L} .
11. (1 pts) A)True or B)False The strategy of solving an ODE using Laplace transforms is to transform the problem from the time domain \mathbf{T} to the (complex) frequency domain \mathbf{F} , solve the transformed problem using algebra instead of calculus, and then transform the solution back to the time domain \mathbf{T} .

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12. (5 pts.) The Laplace transform of the function $f(t) = \begin{cases} 5 & 0 \leq t \leq 8 \\ 0 & t > 8 \end{cases}$

is _____ . _____ A B C D E

Hint: Use the definition. Be careful to handle the limit appropriately as discussed in class.

A) $\frac{8}{s}$ B) $\frac{-8}{s}$ C) $\frac{8}{s}e^{-5s}$ D) $\frac{-8}{s}e^{-5s}$ E) $\frac{8}{s}(1+e^{-5s})$ AB) $\frac{8}{s}(1-e^{-5s})$ AC) $\frac{8}{s}(e^{-5s}-1)$

AD) $\frac{5}{s}$ AE) $\frac{-5}{s}$ BC) $\frac{5}{s}e^{-8s}$ BD) $\frac{-5}{s}e^{-8s}$ BE) $\frac{5}{s}(1+e^{-8s})$ CD) $\frac{5}{s}(1-e^{-8s})$

CE) $\frac{5}{s}(e^{-8s}-1)$ ABC) $\frac{5}{s}(1-e^{8s})$ ABD) None of the above.

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions.
Compute the Laplace transform of the following functions.

13. (4 pts.) $f(t) = 2t + 3t^2$ $\mathcal{L}(f) =$ _____. _____ A B C D E

14. (4 pts.) $f(t) = 2e^{2t} + 3e^{-3t}$ $\mathcal{L}(f) =$ _____. _____ A B C D E

15 (4 pts.) $f(t) = 2 \sin(2t) + 3 \cos(3t)$ $\mathcal{L}(f) =$ _____. _____ A B C D E

Possible answers this page

A) $\frac{2}{s} + \frac{3}{s^2}$ B) $\frac{2}{s} - \frac{3}{s^2}$ C) $\frac{2}{s^2} + \frac{3}{s^3}$ D) $\frac{2}{s^2} - \frac{3}{s^3}$ E) $\frac{2}{s^2} + \frac{6}{s^3}$ AB) $\frac{2}{s^2} - \frac{6}{s^3}$

AC) $\frac{2}{s+2} + \frac{3}{s+3}$ AD) $\frac{2}{s-2} + \frac{3}{s+3}$ AE) $\frac{2}{s+2} + \frac{3}{s-3}$ BC) $\frac{2}{s-2} + \frac{3}{s-3}$

BD) $\frac{2}{(s-2)^2} + \frac{3}{(s+3)^2}$ BE) $\frac{2}{s^2+2} + \frac{3s}{s^2+3}$ CD) $\frac{2s}{s^2+2} + \frac{3}{s^2+3}$ CE) $\frac{4}{s^2+4} + \frac{3s}{s^2+9}$

DE) $\frac{2s}{s^2+4} + \frac{9}{s^2+9}$ ABC) $\frac{4}{s^2-4} + \frac{3s}{s^2-9}$ ABD) $\frac{2s}{s^2-4} + \frac{9}{s^2-9}$ ABE) None of the above.

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DEFINITION. Let $f: X \rightarrow Y$. Then f is one-to-one if $\forall x_1, x_2 \in X$ we have

16.(2 pts.) _____ A B C D E implies 17(2pt) _____ A B C D E

THEOREM. Let $T: V \rightarrow W$ be a linear operator where V and W are vector spaces over the same field \mathbf{K} . If the null space N_T is $\{\vec{0}\}$, then T is a one-to-one mapping.

Proof. We begin our proof of the theorem by first proving the following lemma:

Lemma. If $N_T = \{\vec{0}\}$ and $T(\vec{v}_1) = \vec{0}$, then $\vec{v}_1 = \vec{0}$.

Proof of lemma: Let us assume $N_T = \{\vec{0}\}$ and $T(\vec{v}_1) = \vec{0}$. By the definition of the null space we have

that $N_T = \{ \vec{v} \in V: 18.(1 pt.) \text{_____ A B C D E} \}$ so that $T(\vec{v}_1) = \vec{0}$ implies that

$\vec{v}_1 \in N_T$. Since N_T contains 19.(1 pt.) _____ A B C D E, we have that $\vec{v}_1 = \vec{0}$ as was to be proved. QED for lemma.

Having finished the proof of the lemma, we now finish the proof of the theorem. To show that T

is one-to-one, for $\vec{v}_1, \vec{v}_2 \in V$ we assume 20.(1 pt.) _____ A B C D E

and show that 21.(1 pt.) _____. _____ A B C D E. We use the STATEMENT/REASON format.

STATEMENT

REASON

$T(\vec{v}_1) = T(\vec{v}_2)$

22. (1 pt.) _____ A B C D E

23. (1pt.) _____ A B C D E Vector algebra in W

$T(\vec{v}_1 - \vec{v}_2) = \vec{0}$

24(1 pt.) _____ A B C D E

$\vec{v}_1 - \vec{v}_2 = \vec{0}$

25(1 pt.) _____ A B C D E

$\vec{v}_1 = \vec{v}_2$

Vector algebra in V

Hence T is one-to-one as was to be proved.

QED for the theorem.

Possible answers for this page: A) $f(x_1 + x_2) = 0$ B) $f(x_1) = f(x_2)$ C) $x_1 = x_2$ D) $x_1 + x_2 = 0$

E) $f(x_1) + f(x_2) = 0$ AB) $T(\vec{v}_1) = \vec{0}$ AC) $T(\alpha \vec{v}_1) = \alpha T(\vec{v}_1)$ AD) $T(\vec{v}) = \vec{0}$ AE) $T(\vec{v}_1) = T(\vec{v}_2)$

BC) Hypothesis (or Given) BD) only the zero vector BE) The lemma proved above

CD) Vector algebra in V CE) Vector algebra in W DE) only the vector \vec{v}_1 ABC) $\vec{v}_1 = \vec{v}_2$

ABD) $T(\vec{v}_1 - \vec{v}_2)$ ABE) $T(\vec{v}_1 - \vec{v}_2) = \vec{0}$ BCD) $T(\vec{v}_1 + \vec{v}_2) = \vec{0}$ BCE) $\vec{v}_1 = \vec{0}$ BDE) T is a one-to-one mapping

CDE) T is a linear operator ABCD) Definition of T ABCE) Theorems from Calculus

ACDE) Definition of f BCDE) None of the above.

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions.

Compute the inverse Laplace transform of the following functions.

26. (4 pts.) $F(s) = \frac{2}{s} + \frac{3}{s+2}$ $\mathcal{L}^{-1}\{F\} =$ _____. _____ A B C D E

27. (4 pts.) $F(s) = \frac{2s+4}{s^2+9}$ $\mathcal{L}^{-1}\{F\} =$ _____. _____ A B C D E

28. (4 pts.) $F(s) = \frac{2s+3}{s^2-2s+2}$ $\mathcal{L}^{-1}\{F\} =$ _____. _____ A B C D E

- A) $2 + 3e^{2t}$ B) $2 + 3e^{-2t}$ C) $2 - 3e^{2t}$ D) $2 - 3e^{-2t}$ E) $2 + e^{-2t}$ AB) $2 \cos 3t + 4 \sin 3t$
 AC) $2 \cos 3t - 4 \sin 3t$ AD) $2 \cos 3t + (4/3) \sin 3t$ AE) $3 \cos 3t - (4/3) \sin 3t$
 BC) $2 \cos t + 3 \sin t$ BD) $2e^t \cos t + 5e^t \sin t$ BE) $2e^t \cos t - 5e^t \sin t$
 CD) $2e^t \cos t + e^t \sin t$ CE) $2e^t \cos t - e^t \sin t$ DE) None of the above

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions. Also, circle your answer.

Consider the IVP: ODE $y'' + 4y = 0$ IC's $y(0) = 2, y'(0) = 3$ ($y(0) = 3, y'(0) = 2$)

Let $Y = \mathcal{L}\{y(t)\}(s)$.

29. (3 pts.) As discussed in class (attendance is mandatory), taking the Laplace transform of the ODE and using the initial conditions we may

obtain _____ . _____ A B C D E

Be careful, if you miss this question, you will also miss the next question.

A) $s^2Y + 2s + 3 + 4Y = 0$ B) $s^2Y + 2s + 3 - 4Y = 0$ C) $s^2Y - 2s - 3 + 4Y = 0$

D) $s^2Y - 2s - 3 - 4Y = 0$ E) $s^2Y + 3s + 2 + 4Y = 0$ AB) $s^2Y + 3s + 2 - 4Y = 0$

AC) $s^2Y - 3s - 2 + 4Y = 0$ AD) $s^2Y - 3s - 2 - 4Y = 0$ AE) $s^2Y - 2s + 4Y = 0$

BC) $s^2Y - s - 3 + 4Y = 0$ BD) None of the above

30. (3 pts.) The Laplace transform of the solution to the IVP

is $Y =$ _____ . _____ A B C D E

A) $\frac{2s+3}{s^2+4}$ B) $\frac{2s+3}{s^2-4}$ C) $\frac{2s+3}{s^2+4}$ D) $\frac{2s+3}{s^2-4}$ E) $\frac{3s+2}{s^2+4}$ AB) $\frac{2s+3}{s^2-4}$

AC) $\frac{3s+2}{s^2+4}$ AD) $\frac{2s+3}{s^2-4}$ AE) $\frac{2s}{s^2+4}$ BC) $\frac{2s-3}{s^2+4}$ BD) None of the above

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions. Also, circle your answer.

Consider the system of ode's $x_1' = 3x_1 + 2x_2$
 $x_2' = 2x_1 - 2x_2$

31. (1pt.) Solving the first equation for x_2 we obtain

$x_2 =$ _____ . _____ A B C D E

A) $(3/2)x_1' + (1/2)x_1$ B) $(3/2)x_1' - (1/2)x_1$ C) $-(3/2)x_1' + (1/2)x_1$ D) $-(3/2)x_1' - (1/2)x_1$

E) $(3/2)x_1' + 2x_1$ AB) $2x_1' - x_1$ AC) $-2x_1' + x_1$ AD) $-2x_1' - x_1$ AE) $2x_1' + 2x_1$

BC) $2x_1' - 2x_1$ BD) $-2x_1' + 2x_1$ BE) $x_1' - 2x_1$ CD) None of the above.

32. (5 pts.) Using the procedure illustrated in class (attendance is mandatory), eliminate x_2 in the system to obtain a single second order ODE in x_1 . The ODE obtained by the process discussed

in class is _____ . _____ A B C D E

A) $x_1'' + 5x_1' + 2x_1 = 0$ B) $x_1'' + 5x_1' - 2x_1 = 0$ C) $x_1'' + 5x_1' + 10x_1 = 0$ D) $x_1'' + 5x_1' - 10x_1 = 0$ E) x_1''

$-5x_1' + 2x_1 = 0$ AB) $x_1'' - 5x_1' - 2x_1 = 0$ AC) $x_1'' - 5x_1' + 10x_1 = 0$ AD) $x_1'' - 5x_1' - 10x_1 = 0$ AE) $x_1'' + x_1'$

$+ 2x_1 = 0$ BC) $x_1'' + x_1' - 2x_1 = 0$ BD) $x_1'' + x_1' + 10x_1 = 0$ BE) $x_1'' + x_1' - 10x_1 = 0$

CD) $x_1'' - x_1' + 2x_1 = 0$ CE) $x_1'' - x_1' - 2x_1 = 0$ DE) $x_1'' - x_1' + 10x_1 = 0$ ABC) $x_1'' - x_1' - 10x_1 = 0$

ABD) None of the above.

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33. (4 pts.) Consider the scalar equation $u'' + 4u' + 2u = 0$ where $u = u(t)$ (i.e. the dependent variable u is a function of the independent variable t so that $u' = du/dt$ and $u'' = d^2u/dt^2$). Convert this to a system of two first order equations by letting $u = x$ and $u' = y$. (I.e. obtain two first order scalar equations in x and y . You may think of $u = x$ as the position and $u' = y$ as the velocity of a point particle). Now write this system of two scalar equations in the vector form

$$\vec{x}' = A\vec{x} \quad \text{where } \vec{x} = \begin{bmatrix} x \\ y \end{bmatrix} \quad \text{and } A \text{ is a } 2 \times 2 \text{ matrix given by}$$

A = _____ . _____ A B C D E

- A) $\begin{bmatrix} 1 & 0 \\ 2 & 4 \end{bmatrix}$ B) $\begin{bmatrix} 1 & 0 \\ -2 & 4 \end{bmatrix}$ C) $\begin{bmatrix} 1 & 0 \\ 2 & -4 \end{bmatrix}$ D) $\begin{bmatrix} 1 & 0 \\ -2 & -4 \end{bmatrix}$ E) $\begin{bmatrix} 1 & 0 \\ 4 & 2 \end{bmatrix}$ AB) $\begin{bmatrix} 1 & 0 \\ 4 & -2 \end{bmatrix}$
- AC) $\begin{bmatrix} 1 & 0 \\ 4 & -2 \end{bmatrix}$ AD) $\begin{bmatrix} 1 & 0 \\ -4 & 2 \end{bmatrix}$ AE) $\begin{bmatrix} 1 & 0 \\ -4 & -2 \end{bmatrix}$ BC) $\begin{bmatrix} 0 & 1 \\ 2 & 4 \end{bmatrix}$ BD) $\begin{bmatrix} 0 & 1 \\ -2 & 4 \end{bmatrix}$ BE) $\begin{bmatrix} 0 & 1 \\ 2 & -4 \end{bmatrix}$
- CD) $\begin{bmatrix} 0 & 1 \\ -2 & -4 \end{bmatrix}$ CE) $\begin{bmatrix} 0 & 1 \\ 4 & 2 \end{bmatrix}$ DE) $\begin{bmatrix} 1 & 0 \\ 4 & -2 \end{bmatrix}$ ABC) $\begin{bmatrix} 0 & 1 \\ 4 & -2 \end{bmatrix}$ ABD) $\begin{bmatrix} 0 & 1 \\ -4 & 2 \end{bmatrix}$
- ABE) $\begin{bmatrix} 0 & 1 \\ -4 & -2 \end{bmatrix}$ BCD) None of the above.

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34. (3 pts.) Let $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} \subseteq V$ where V is a vector space and (*) be the vector equation $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_n\vec{v}_n = \vec{0}$. Choose the correct completion of the following:

Definition. The set S is linearly independent

if _____. _____ A B C D E

- A) (*) has only the solution $c_1 = c_2 = \dots = c_n = 0$. B) (*) has an infinite number of solutions.
 C) (*) has a solution other than the trivial solution. D) (*) has at least two solutions.
 E) (*) has no solution. AB) the associated matrix is nonsingular.
 AC) the associated matrix is singular. AD) None of the above

35. (3 pts.) Now let $S_1 = \{ [x_1(t), y_1(t), z_1(t)]^T, [x_2(t), y_2(t), z_2(t)]^T, \dots, [x_n(t), y_n(t), z_n(t)]^T \}$
 $\subseteq \mathcal{A}(\mathbf{R}, \mathbf{R}^3)$ and (***) be the "vector" equation
 $c_1 [x_1(t), y_1(t), z_1(t)]^T + c_2 [x_2(t), y_2(t), z_2(t)]^T + \dots + c_n [x_n(t), y_n(t), z_n(t)]^T = [0, 0, 0]^T \quad \forall t \in \mathbf{R}$
 Apply the definition above to the space of time varying "vectors" $\mathcal{A}(\mathbf{R}, \mathbf{R}^3)$. That is,
 by the definition above the set $S_1 \subseteq \mathcal{A}(\mathbf{R}, \mathbf{R}^3)$ is linearly independent

if _____. _____ A B C D E

- A) (***) has only the solution $c_1 = c_2 = \dots = c_n = 0$. B) (***) has an infinite number of solutions
 C) (***) has a solution other than the trivial solution. D) (***) has at least two solutions.
 E) (***) has no solution. AB) the associated matrix is nonsingular.
 AC) the associated matrix is singular. AD) None of the above

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36. (4 pts.) You are to determine Directly Using the Definition (DUD) if the following set of time varying "vectors" are linearly independent. Let $S = \{\bar{x}_1(t), \bar{x}_2(t)\} \subseteq \mathcal{A}(\mathbf{R}, \mathbf{R}^2)$ where

$$\bar{x}_1(t) = \begin{bmatrix} 3e^t \\ 4e^t \end{bmatrix} \quad \text{and} \quad \bar{x}_2(t) = \begin{bmatrix} 6e^t \\ 8e^{-t} \end{bmatrix}. \quad \text{Then } S$$

is _____. _____ A B C D E

A) linearly independent as $c_1 \bar{x}_1(t) + c_2 \bar{x}_2(t) = [0,0]^T \quad \forall t \in \mathbf{R}$ implies $c_1 = c_2 = 0$.

B) linearly independent as $-2 \bar{x}_1(t) + \bar{x}_2(t) = [0,0]^T \quad \forall t \in \mathbf{R}$.

C) linearly independent as the associated matrix is nonsingular.

D) linearly independent as the associated matrix is singular.

E) linearly dependent as $c_1 \bar{x}_1(t) + c_2 \bar{x}_2(t) = [0,0]^T \quad \forall t \in \mathbf{R}$ implies $c_1 = 0$ and $c_2 = 0$.

D) linearly dependent as $-2 \bar{x}_1(t) + \bar{x}_2(t) = [0,0]^T \quad \forall t \in \mathbf{R}$.

AB) linearly dependent as the associated matrix is nonsingular.

AC) linearly dependent as the associated matrix is singular.

AD) neither linearly independent or linearly dependent as the definition does not apply.

AE) None of the above statements are true.

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Using the procedure illustrated in class (attendance is mandatory) find the eigenvalues of

$$A = \begin{bmatrix} i & 4 \\ 0 & 1 \end{bmatrix} \in \mathbb{C}^{2 \times 2}.$$

37. (3 pts.) A polynomial $p(\lambda)$ where solving $p(\lambda) = 0$ yields the eigenvalues of A can be written

as $p(\lambda) =$ _____ . _____ A B C D E

- A) $(i+\lambda)(1+\lambda)$ B) $(i+\lambda)(1-\lambda)$ C) $(i-\lambda)(1+\lambda)$ D) $(i-\lambda)(1-\lambda)$ E) $(i+\lambda)(2+\lambda)$ AB) $(i+\lambda)(2-\lambda)$
 AC) $(i-\lambda)(2+\lambda)$ AD) $(i-\lambda)(2-\lambda)$ AE) $(2i+\lambda)(1+\lambda)$ BC) $(2i+\lambda)(1-\lambda)$ BD) $(2i-\lambda)(1+\lambda)$
 BE) $(2i-\lambda)(1-\lambda)$ CD) $(2i+\lambda)(2+\lambda)$ CE) $(2i+\lambda)(2-\lambda)$ DE) $(2i-\lambda)(2+\lambda)$ ABC) $(2i-\lambda)(2-\lambda)$
 ABD) $(3i-\lambda)(2+\lambda)$ ABE) None of the above.

$$p(\lambda) =$$

38. (1 pt.) The degree of $p(\lambda)$ is _____. _____ A B C D E A) 1 B) 2 C) 3 D)
 4 E) 5 AB) 6 AC) 7 AD) None of the above.

39. (1 pt.) Counting repeated roots, the number of eigenvalues of A

is _____. _____ A B C D E A) 0 B) 1 C) 2 D) 3 E) 4 AB) 5
 AC) 6 AD) 7 AE) 8 BC) None of the above

40. (3 pts.) The eigenvalues of A can be written as _____. _____ A B C D E

- A) $\lambda_1 = 1, \lambda_2 = i$ B) $\lambda_1 = 1, \lambda_2 = -i$ C) $\lambda_1 = -1, \lambda_2 = i$ D) $\lambda_1 = -1, \lambda_2 = -i$ E) $\lambda_1 = 2, \lambda_2 = i$
 AB) $\lambda_1 = 2, \lambda_2 = -i$ AC) $\lambda_1 = -2, \lambda_2 = i$ AD) $\lambda_1 = -2, \lambda_2 = -i$ AE) $\lambda_1 = 1, \lambda_2 = 2i$
 BC) $\lambda_1 = 1, \lambda_2 = -2i$ BD) $\lambda_1 = -1, \lambda_2 = 2i$ BE) $\lambda_1 = -1, \lambda_2 = -2i$ CD) $\lambda_1 = 2, \lambda_2 = 2i$
 CE) $\lambda_1 = 2, \lambda_2 = -2i$ DE) $\lambda_1 = -2, \lambda_2 = 2i$ ABC) $\lambda_1 = -2, \lambda_2 = -2i$ ABD) None of the above

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Note that $\lambda_1 = 2$ is an eigenvalue of the matrix $A = \begin{bmatrix} 3 & -1 \\ 4 & -2 \end{bmatrix}$

41. (4 pts.) Using the conventions discussed in class (attendance is mandatory), a basis B for

the eigenspace associated with λ_1 is B = _____ . ____ A B C D E

A) $\{[1,1]^T, [4,4]^T\}$ B) $\{[1,1]^T\}$ C) $\{[1,2]^T\}$ D) $\{[1,2]^T, [4,8]^T\}$ E) $\{[2,1]^T\}$

AB) $\{[1,3]^T\}$ AC) $\{[1,4]^T\}$ AD) $\{[4,1]^T\}$ AE) $\{[3,1]^T\}$ BC) $\{[1,-1]^T, [4,4]^T\}$

BD) $\{[1,-1]^T\}$ BE) $\{[1,-2]^T\}$ CD) $\{[1,-2]^T, [4,8]^T\}$ CE) $\{[2,1]^T\}$ DE) $\{[1,3]^T\}$

ABC) $\{[1,-4]^T\}$ ABD) $\{[4,-1]^T\}$ ABE) $\{[3,-1]^T\}$

ACD) $\lambda = 2$ is not an eigenvalue of the matrix A

ACE) $\lambda = -1$ is not an eigenvalue of the matrix A ADE) None of the above is correct.

42. (1pt.) Although there are an infinite number of eigenvectors associated with any eigenvalue, since the eigenspace associated with λ_1 is one dimensional and we have developed conventions for selecting a basis for the eigenspace associated with λ_1 , we say that the eigenvector associated

with λ_1 is _____ . ____ A B C D E

A) $\{[1,1]^T, [4,4]^T\}$ B) $\{[1,1]^T\}$ C) $\{[1,2]^T\}$ D) $\{[1,2]^T, [4,8]^T\}$ E) $\{[2,1]^T\}$

AB) $\{[1,3]^T\}$ AC) $\{[1,4]^T\}$ AD) $\{[4,1]^T\}$ AE) $\{[3,1]^T\}$ BC) $\{[1,-1]^T, [4,4]^T\}$

BD) $\{[1,-1]^T\}$ BE) $\{[1,-2]^T\}$ CD) $\{[1,-2]^T, [4,8]^T\}$ CE) $\{[2,1]^T\}$ DE) $\{[1,3]^T\}$

ABC) $\{[1,-4]^T\}$ ABD) $\{[4,-1]^T\}$ ABE) $\{[3,-1]^T\}$

ACD) $\lambda_1 = 2$ is not an eigenvalue of the matrix A

ACE) $\lambda_1 = -1$ is not an eigenvalue of the matrix A ADE) None of the above is correct.

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True or false. Eigenvalue Problems for Complex Matrices.

Assume A is an $n \times n$ square matrix of possibly complex numbers. Under this hypothesis, determine which of the following is true and which is false.

43. (1 pt.) A) True or B) False A real square matrix may have only real eigenvalues.
44. (1 pt.) A) True or B) False A real square matrix will always have distinct eigenvalues.
45. (1 pt.) A) True or B) False A real symmetric matrix will have only real eigenvalues.
46. (1 pt.) A) True or B) False A Hermitian matrix will always have real eigenvalues.
47. (1 pt.) A) True or B) False A Hermitian matrix will always have distinct eigenvalues.

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Follow the instructions on the Exam Cover Sheet for Fill-in-the Blank/Multiple Choice questions. Also, circle your answer.

TABLE

Let the 2x2 matrix A have the eigenvalue table

Eigenvalues Eigenvectors

Let $L: \mathcal{A}(\mathbf{R}, \mathbf{R}^2) \rightarrow \mathcal{A}(\mathbf{R}, \mathbf{R}^2)$ be defined by $L[\bar{x}] = \bar{x}' - A\bar{x}$

$r_1 = 1$

$$\bar{\xi}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

and let the null space of L be N_L

$r_2 = 2$

$$\bar{\xi}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

48. (1 pt). The dimension of N_L is _____. _____ A B C D E
 A) 1 B) 2 C) 3 D) 4 E) 5 AB) 6 AC) 7 AD) None of the above.

49. (3 pts.) A basis for the null space of L is _____. _____ A B C D E

A) $B = \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^t, \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t} \right\}$ B) $B = \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-t}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t} \right\}$ C) $B = \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^t, \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-2t} \right\}$ D) $B = \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-t}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-2t} \right\}$

E) $B = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^t, \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{2t} \right\}$ AB) $B = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-t}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{2t} \right\}$ AC) $B = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^t, \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-2t} \right\}$ AD) $B = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-t}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-2t} \right\}$ AE)

$B = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-t}, \begin{bmatrix} 2 \\ -1 \end{bmatrix} e^{2t} \right\}$ BC) $B = \left\{ \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-t}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-2t} \right\}$ BD) $B = \left\{ \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-t}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{2t} \right\}$ BE) $B = \left\{ \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-t}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{2t} \right\}$ CD)

None of the above

50. (2 pts.) The general solution of $\bar{x}' = A\bar{x}$ is _____. _____ A B C D E

A) $\bar{x}(t) = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t}$ B) $\bar{x}(t) = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{2t}$ C) $\bar{x}(t) = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-2t}$ D) $\bar{x}(t) = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-2t}$

E) $\bar{x}(t) = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^t + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{2t}$ AB) $\bar{x}(t) = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{2t}$ AC) $\bar{x}(t) = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^t + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-2t}$ AD) $\bar{x}(t) = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-2t}$

AE) $\bar{x}(t) = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2 \\ -1 \end{bmatrix} e^{2t}$ BC) $\bar{x}(t) = c_1 \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-2t}$ BD) $\bar{x}(t) = c_1 \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{2t}$

BE) $\bar{x}(t) = c_1 \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{2t}$ CD) None of the above